

Hamiltonian thickness and fault-tolerant spanning rooted path systems of graphs

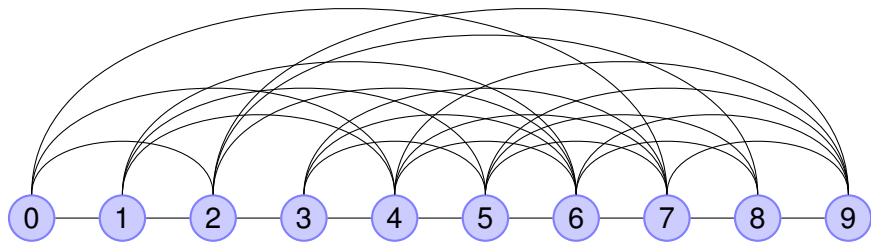
Yinfeng Zhu (祝隐峰)

Shanghai Jiao Tong University

Dec 8, 2015

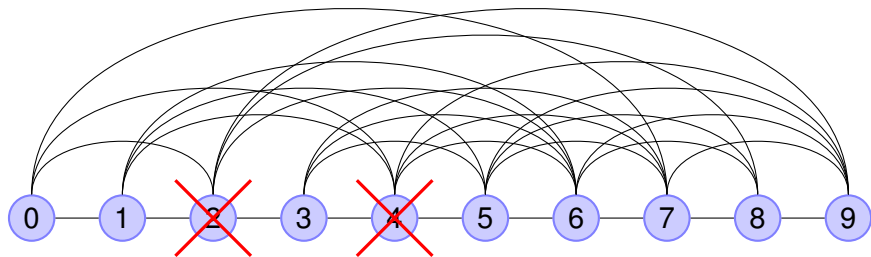
Joint with Yaokun Wu (吴耀琨) & Ziqing Xiang (向子卿)

Spanning connection pattern with fault-tolerance



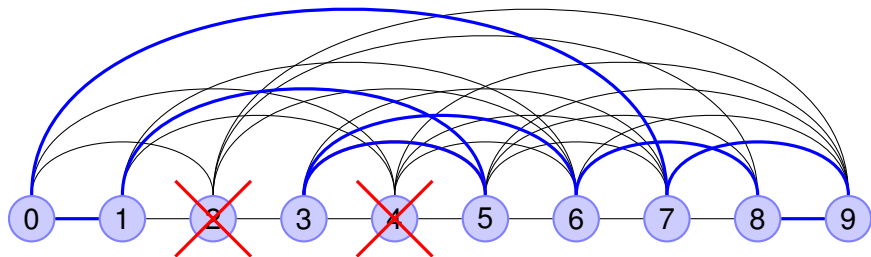
Deleting ≤ 2 vertices always results in a Hamiltonian graph.

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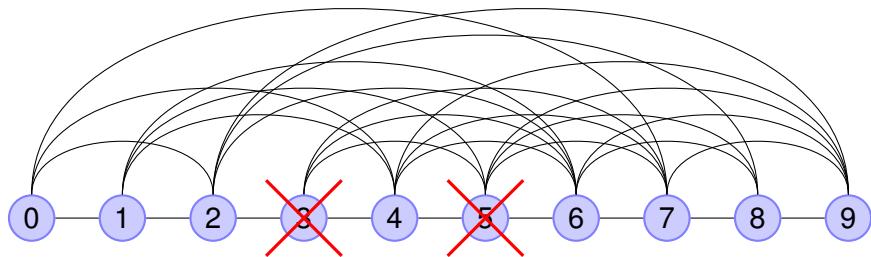
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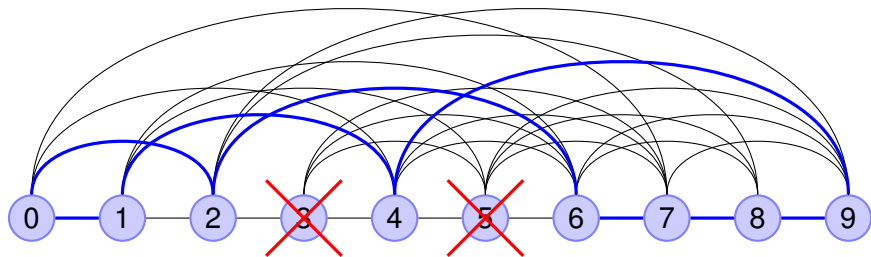
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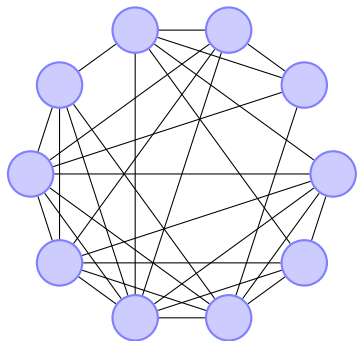
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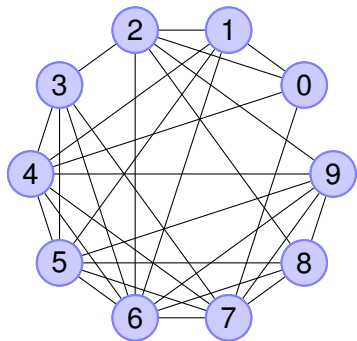


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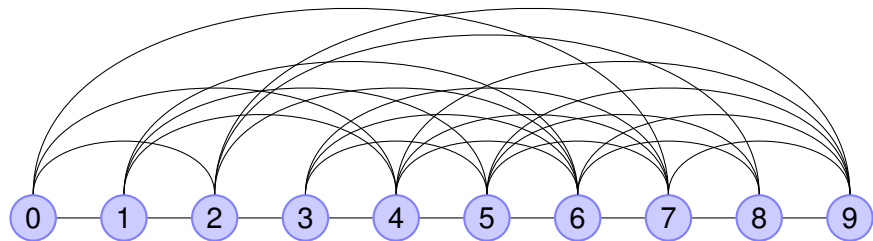
Hamiltonian thickness



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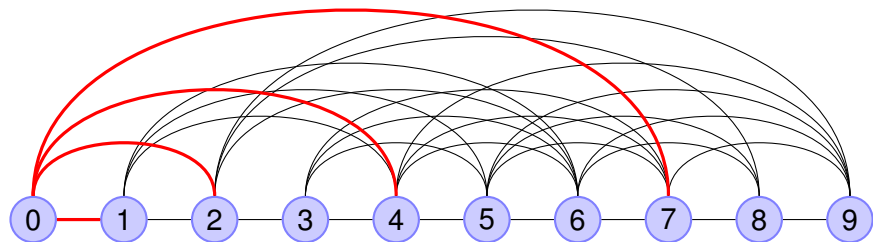


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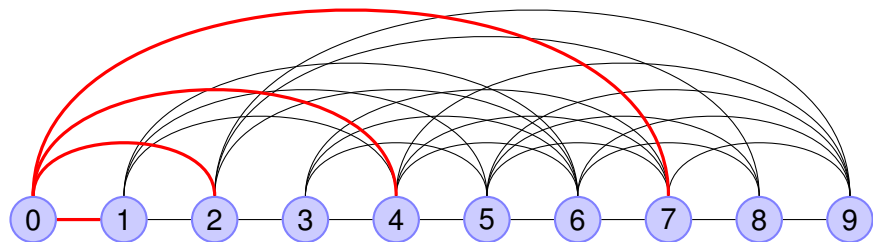
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Hamiltonian thickness



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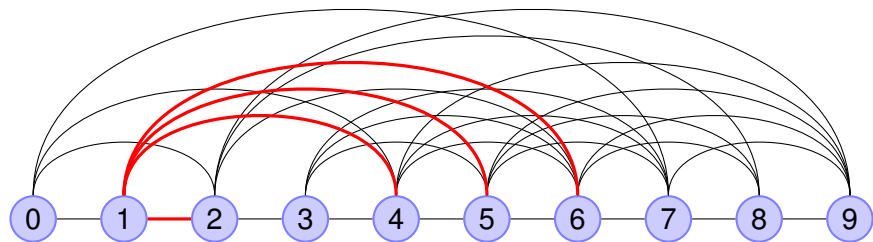
Hamiltonian thickness



≥ 4

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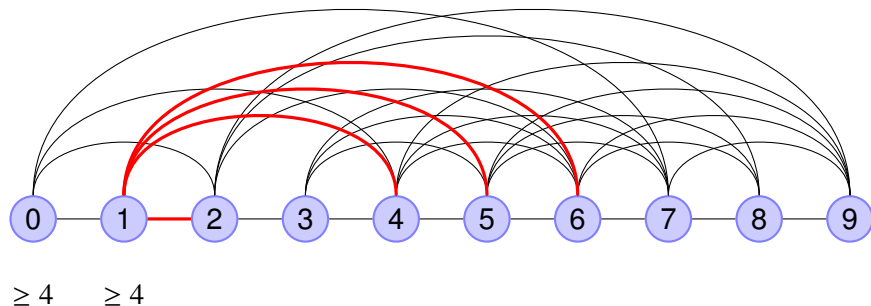
Hamiltonian thickness



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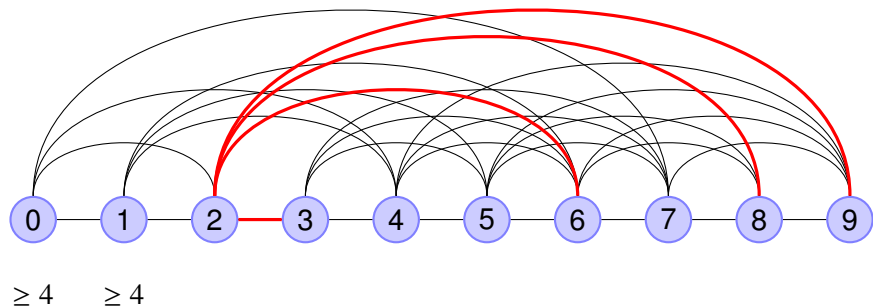
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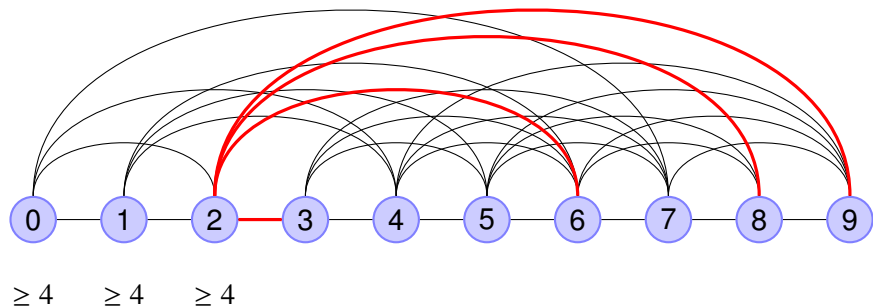
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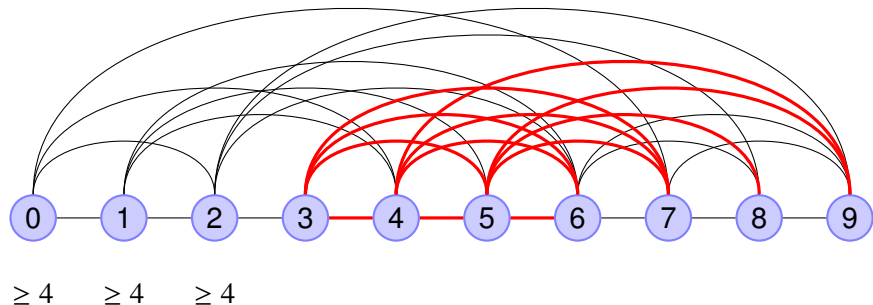
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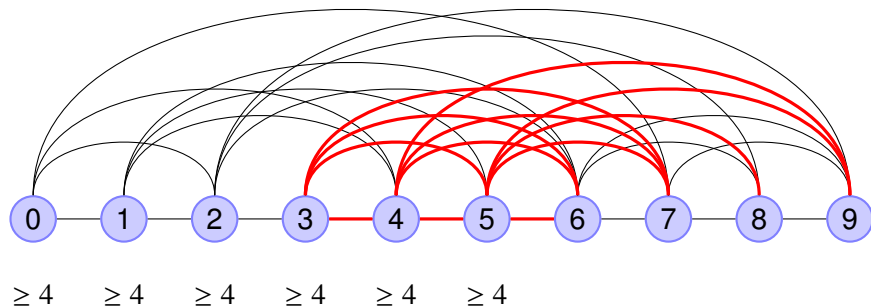
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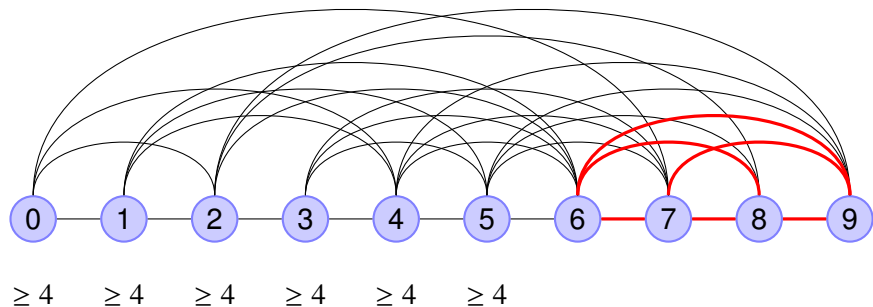
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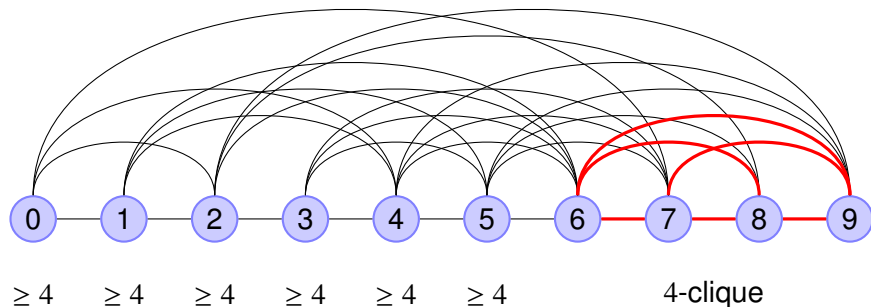
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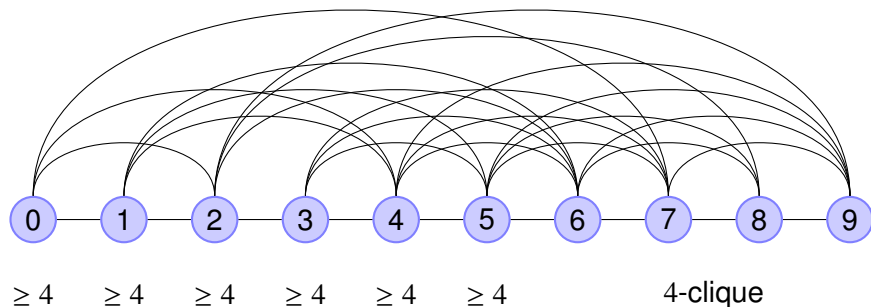
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Definition

A graph G is a **k -thick Hamiltonian graph** if G has a k -thick Hamiltonian vertex ordering.

Path system I

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A path in G with identical endpoints is either a **trivial path** (of length zero) or a **cycle** (of length at least three). For a loop edge $vv \in E_H$, an vv -path in G should be understood as a cycle of length at least 3 but not any trivial path.

Path system II

A **path system of G rooted at E_H** is a set $Q = \{P_e : e \in E_H\}$ of m paths in G such that P_e is an e -path and every two distinct paths in the family intersect only at their possible common endpoints.

Path system II

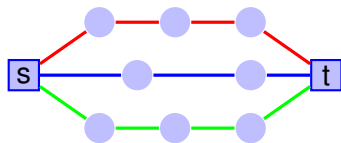
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A path system of G is **spanning** if the union of the vertices of the paths in it is the whole vertex set of G .

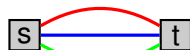
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A spanning 3-rail rooted at E_H

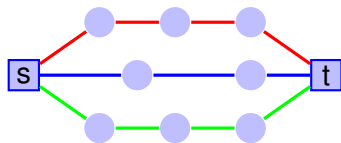


H

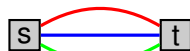
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H

- spanning 1-rail \longleftrightarrow Hamiltonian path
- spanning 2-rail \longleftrightarrow Hamiltonian cycle

f -factor

Let H be a multigraph and $f : V_H \rightarrow \mathbb{N}$ be a map.

An f -factor of H is a multigraph F with

- $V_F = V_H$;
- $E_F \subseteq E_H$;
- $\deg_F(v) = f(v)$ for all $v \in V_F$. (Each loop contributes 2 degrees.)

The multigraph H is f -factor friendly if every g -factor of H can be extended into an f -factor of H by adding edges as long as $g \leq f$.

A path system of G rooted at (H, f)

Let G be a graph with $V_H \subseteq V_G$. A path system of G rooted at (H, f) is a path system of $G - f^{-1}(0)$ rooted at E_F for some f -factor F of H . A path system of G rooted at (H, f) is called **spanning** if every vertex from $V_G \setminus f^{-1}(0)$ appears in some path of the system.

Note that $f^{-1}(0)$ can be thought of as the set of faulty nodes in G .

Question and result

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Which kind of (sparse) graphs have a (spanning) path system rooted at (H, f) ?

We show that G has a (spanning) path system rooted at (H, f) whenever the Hamiltonian thickness of G is no less than some parameter determined by f .

Hamiltonian thickness vs. path system

Suppose that G has a vertex ordering π_1, \dots, π_n with Hamiltonian thickness at least k . Let H be an f -factor friendly multigraph.

Hamiltonian thickness vs. path system

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$$(i) |f^{-1}(0)| + \sum_{v \in V_H} f(v) - \left\lceil \frac{1}{2} \min_{f(v) \neq 0} f(v) \right\rceil + 1$$

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(H is triangle-free and loopless)

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(H is bipartite with $m_H(u, v) \geq \min\{f(u), f(v)\}$)

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If $\pi_1 \notin V_H$, the bounds for thickness should be increased by one.

Hamiltonian thickness vs. spanning path system

If $\pi_n \in V_H$ and $f(\pi_n) \geq 2$, the same bound applies for the existence of a spanning path system.

In remaining cases, we may need to increase the thickness bound by one.

Fault-tolerant spanning k -rail

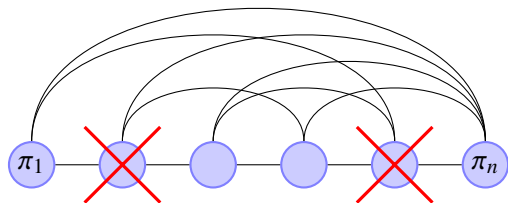
Corollary

Let k and t be integers satisfying $k \geq t \geq 2$ and let G be a graph with a k -thick Hamiltonian vertex ordering π_1, \dots, π_n . For every $C \subseteq \binom{V_G \setminus \{\pi_1, \pi_n\}}{\leq k-t}$, $G - C$ has a spanning t -rail between π_1 and π_n .

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$t = 1, |C| = k - t$, no spanning t -rail between π_1 and π_n in $G - C$.

The greedy strategy, I

We start from a path family \mathcal{P} which consists of $f(v)$ trivial paths at vertex v for all $v \in V_H$ as well as one trivial path at v for all $v \in V_G \setminus V_H$.

At each iteration, we find a suitable edge of G to connect two paths in \mathcal{P} into one and update \mathcal{P} accordingly. We always try to add the edge so that the path family obtained does not violate some obvious conditions for a path family to be further updated into a path system rooted at (H, f) (together with some other paths in $G - V_H$, if that path system is not required to be spanning).

A vertex $v \in V_G$ is **finished** in \mathcal{P} if $v \in V_H$ and v is incident to $\deg_H(v)$ edges in \mathcal{P} or $v \notin V_H$ and v is incident to 2 edges in \mathcal{P} . A vertex $v \in V_G$ is **fresh** in \mathcal{P} if $v \notin V_H$ and v is incident to no edges in \mathcal{P} .

The greedy strategy, II

Let π_1, \dots, π_n be an ordering of V_G with high Hamiltonian thickness.

- (i) Find **the leftmost unfinished vertex in \mathcal{P} , say π_i** . If π_i is fresh or $\pi_i \in V_H$, we choose $P \in \mathcal{P}$ as a trivial path at π_i . Else, we choose P as the unique nontrivial path in \mathcal{P} that contains π_i as an endpoint.
- (ii) We try to find **another unfinished vertex $\pi_j \in N_G(\pi_i)$** and a path $Q \in \mathcal{P}$ containing π_j and connect P and Q by **adding edge $\pi_i\pi_j$** . We should guarantee that the updated path family is still “allowed”.
- (iii) If π_{i+1} is fresh, then we should choose $j = i + 1$.

The greedy strategy, III

Suppose we want to find a spanning path system rooted at (H, f) . We follow two more strategies.

- (i) Whenever possible, we should first try to choose π_j so that the updated path family \mathcal{P} **does not contain a subdivision of any f -factor of H .**
- (ii) Suppose $\pi_n \in V_H$ and $f(\pi_n) \geq 2$. If π_n is not on a nontrivial path in the path family \mathcal{P} yet, then we **choose $j = n$ only when there is no other choice.**

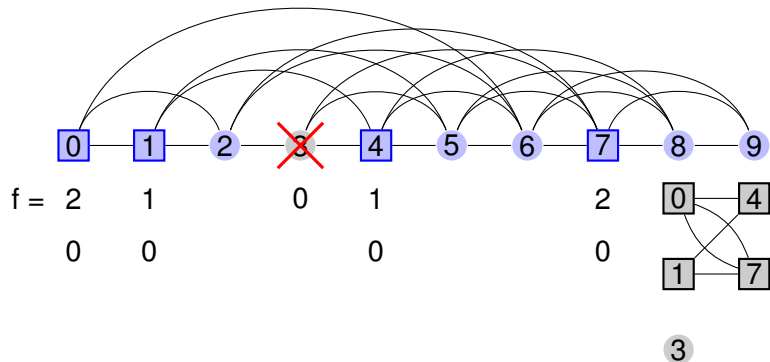
Finding spanning path system

$\mathcal{P} = \{0, 0, 1, 2, 4, 5, 6, 7, 7, 8, 9\}$

$Q = \{\}$

$P = ?$

$Q = ?$



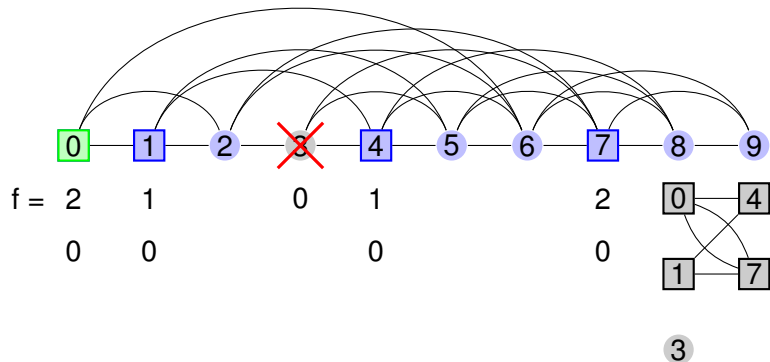
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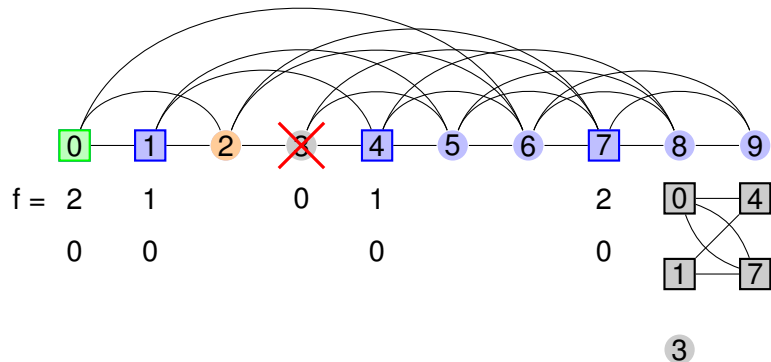
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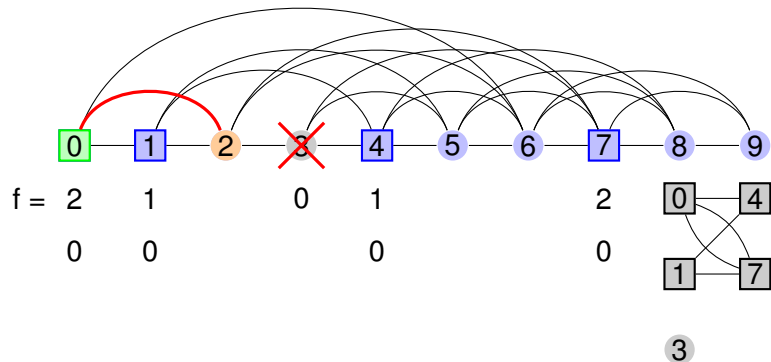
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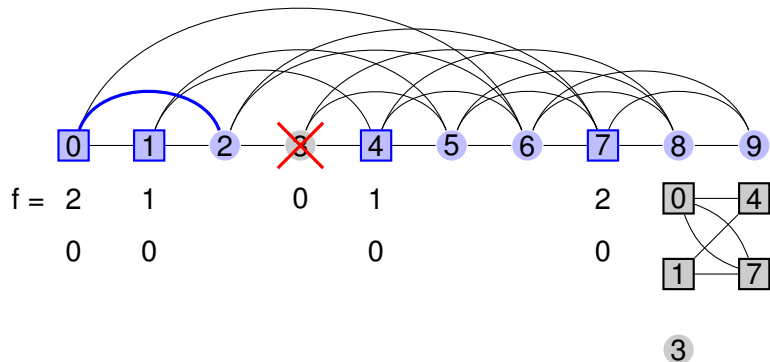
Finding spanning path system

$\mathcal{P} = \{0-2, 0, 1, 4, 5, 6, 7, 7, 8, 9\}$

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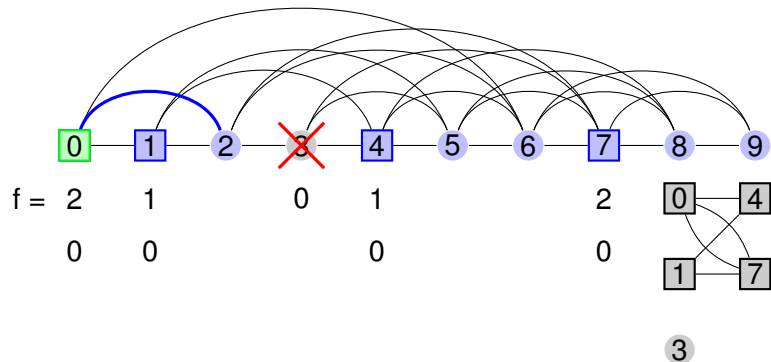
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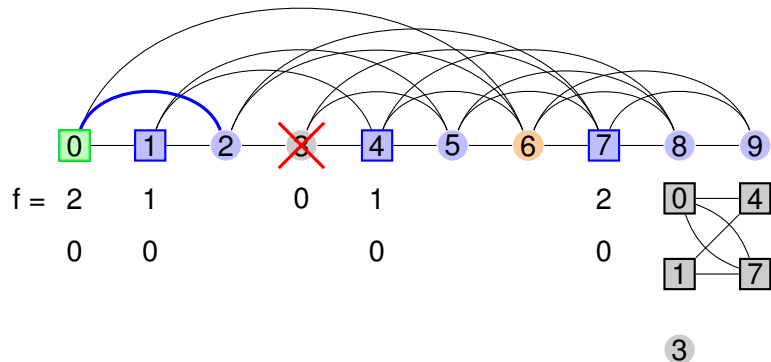
Finding spanning path system

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$P = 0$

$Q = 6$



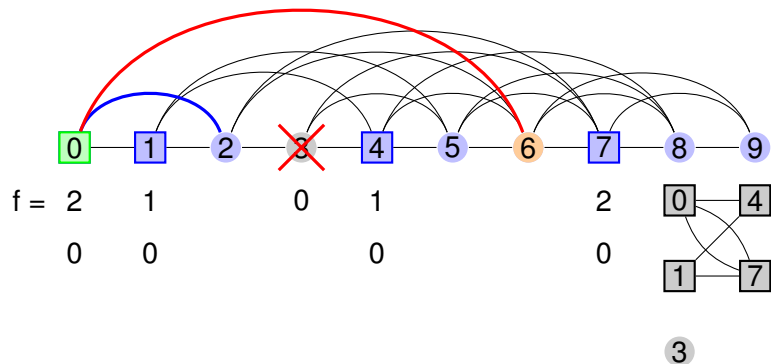
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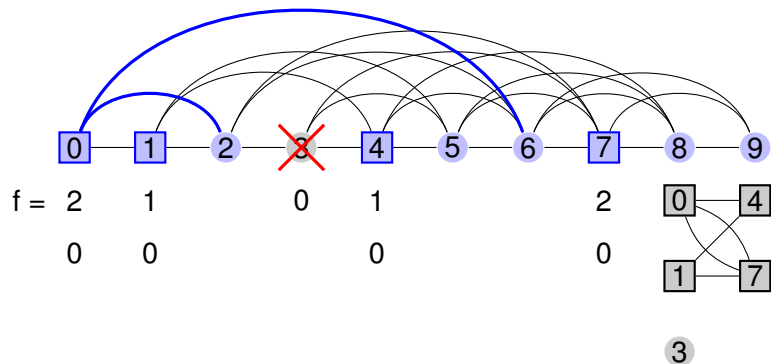
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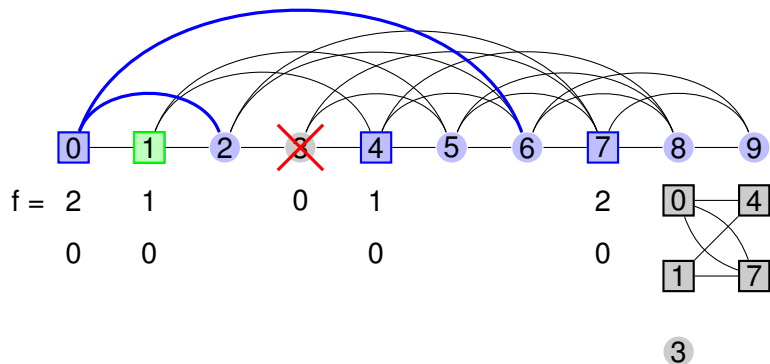
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$Q = ?$



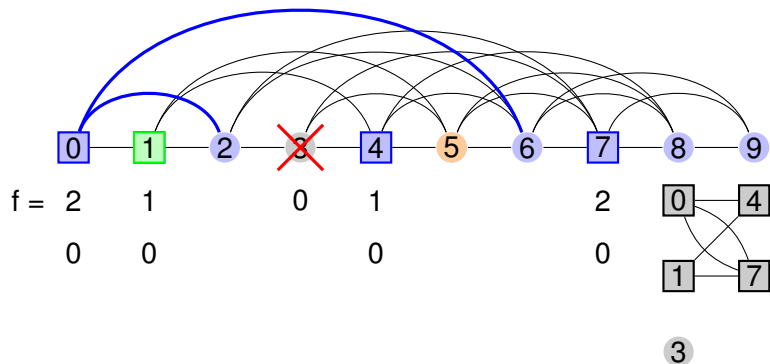
Finding spanning path system

$\mathcal{P} = \{0-2, 0-6, 1, 4, 5, 7, 7, 8, 9\}$

$Q = \{\}$

$P = 1$

$Q = 5$



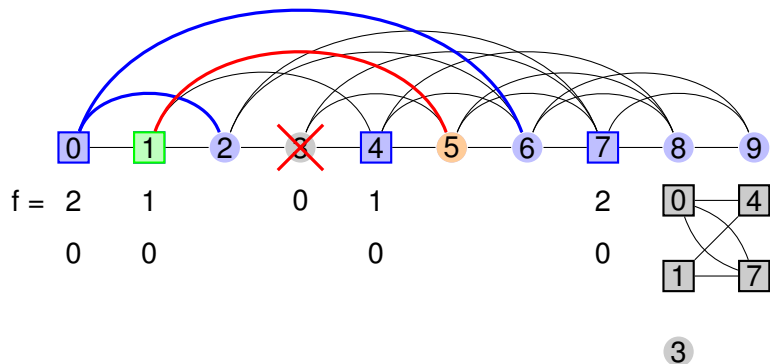
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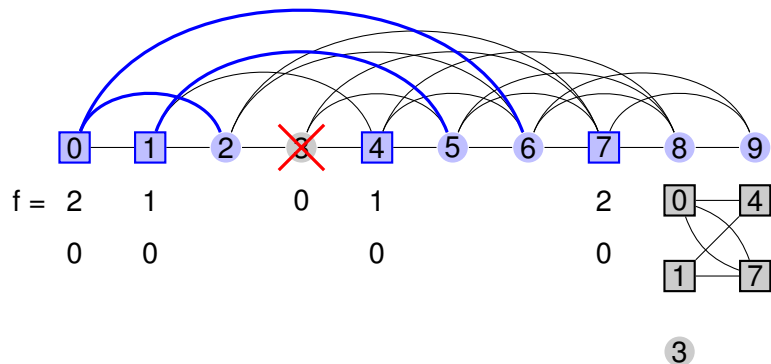
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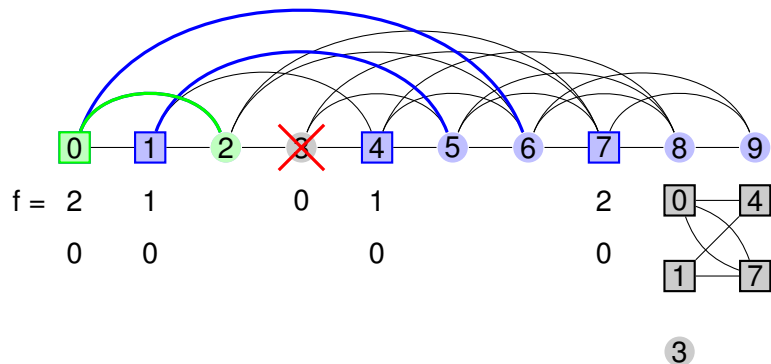
Finding spanning path system

$\mathcal{P} = \{0-2, 0-6, 1-5, 4, 7, 7, 8, 9\}$

$Q = \{\}$

$P = 0-2$

$Q = ?$



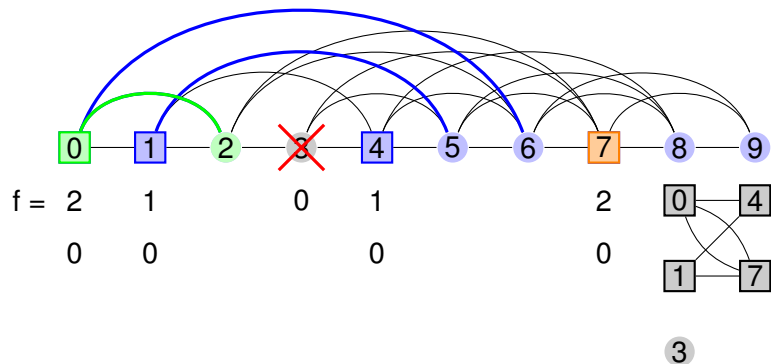
Finding spanning path system

$\mathcal{P} = \{0-2, 0-6, 1-5, 4, 7, 7, 8, 9\}$

$Q = \{\}$

$P = 0-2$

$Q = 7$



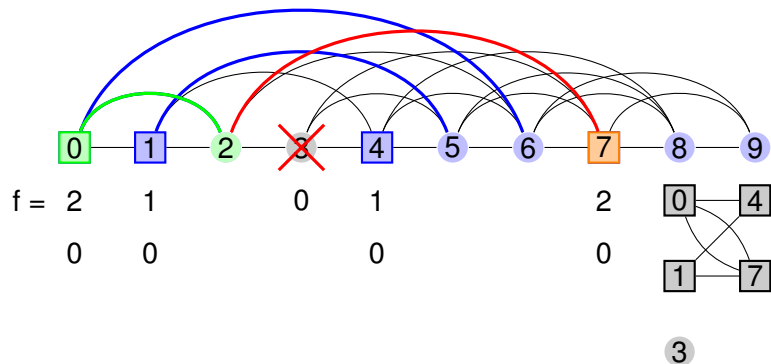
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$P = 0-2$

$Q = 7$



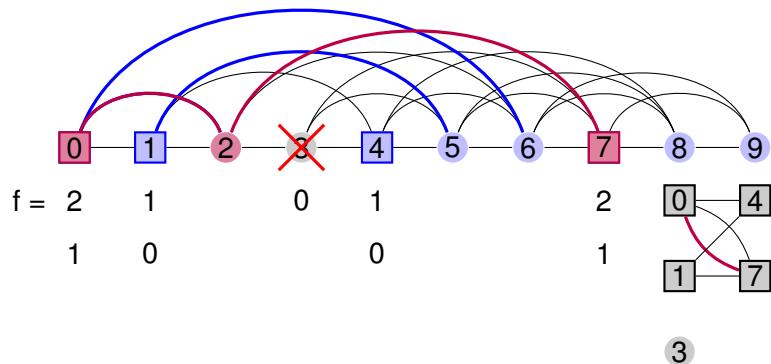
Finding spanning path system

$\mathcal{P} = \{0-6, 1-5, 4, 7, 8, 9\}$

$\mathcal{Q} = \{0-2-7\}$

$\mathcal{P} = ?$

$\mathcal{Q} = ?$



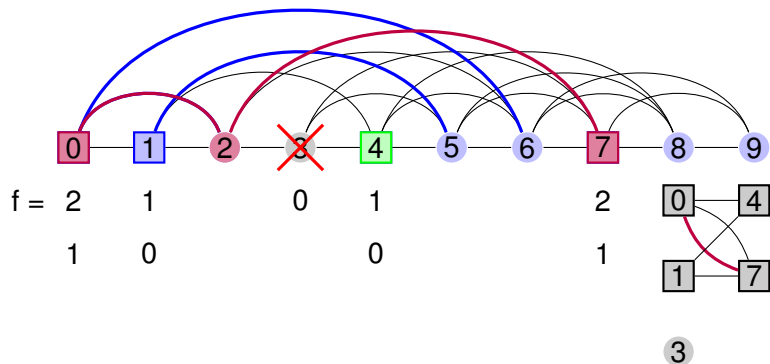
Finding spanning path system

$\mathcal{P} = \{0-6, 1-5, 4, 7, 8, 9\}$

$\mathcal{Q} = \{0-2-7\}$

$P = 4$

$Q = ?$



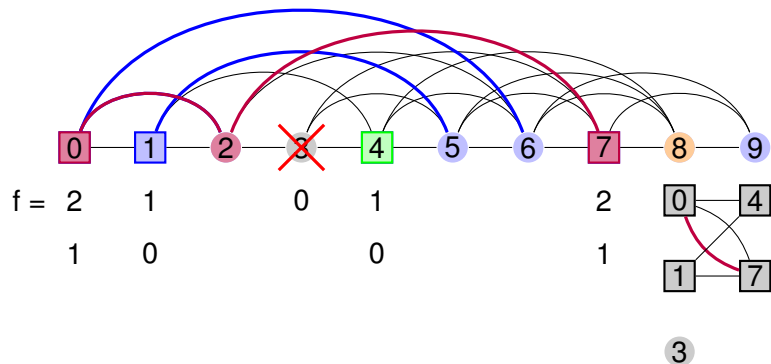
Finding spanning path system

$\mathcal{P} = \{0-6, 1-5, 4, 7, 8, 9\}$

$\mathcal{Q} = \{0-2-7\}$

$P = 4$

$Q = 8$



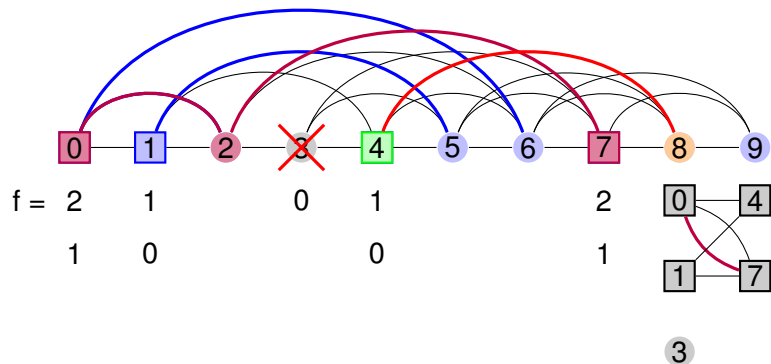
Finding spanning path system

$\mathcal{P} = \{0-6, 1-5, 4, 7, 8, 9\}$

$Q = \{0-2-7\}$

$P = 4$

$Q = 8$



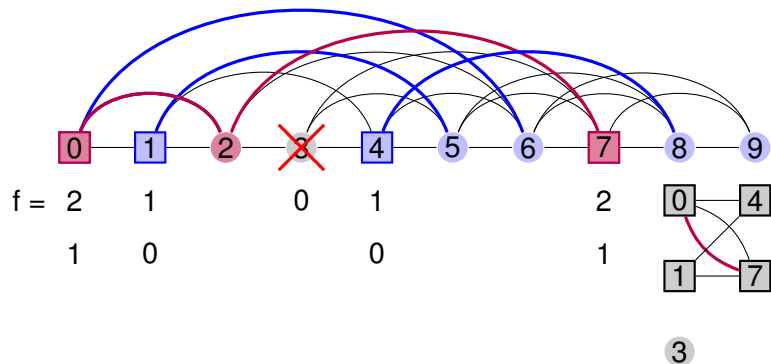
Finding spanning path system

$\mathcal{P} = \{0-6, 1-5, 4-8, 7, 9\}$

$\mathcal{Q} = \{0-2-7\}$

$\mathcal{P} = ?$

$\mathcal{Q} = ?$



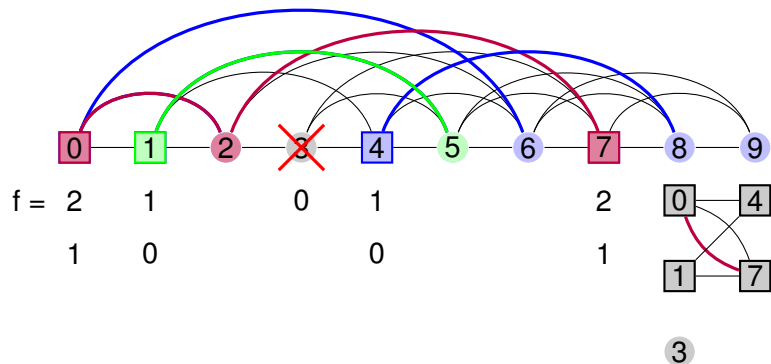
Finding spanning path system

$\mathcal{P} = \{0-6, 1-5, 4-8, 7, 9\}$

$Q = \{0-2-7\}$

$P = 1-5$

$Q = ?$



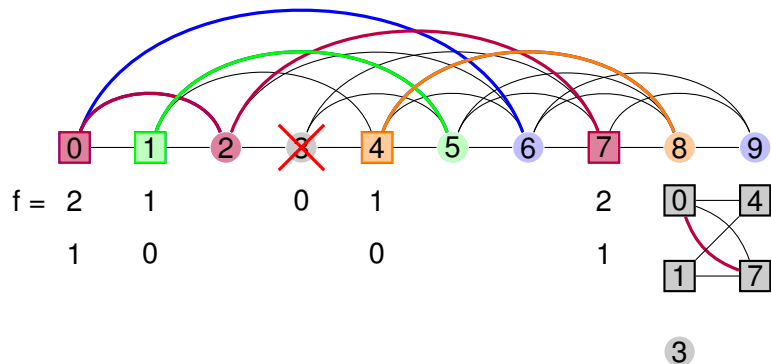
Finding spanning path system

$\mathcal{P} = \{0-6, 1-5, 4-8, 7, 9\}$

$Q = \{0-2-7\}$

$P = 1-5$

$Q = 4-8$



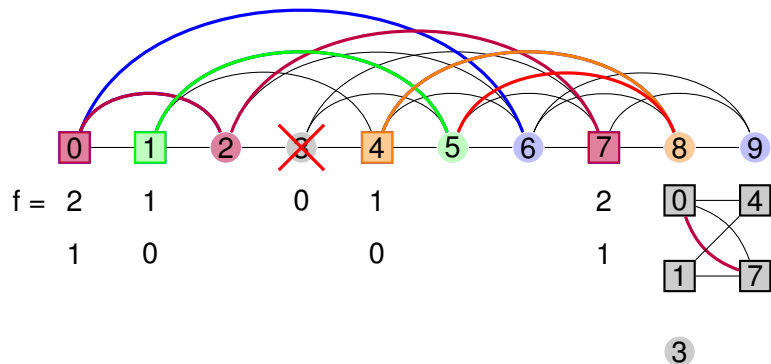
Finding spanning path system

$\mathcal{P} = \{0-6, 1-5, 4-8, 7, 9\}$

$Q = \{0-2-7\}$

$P = 1-5$

$Q = 4-8$



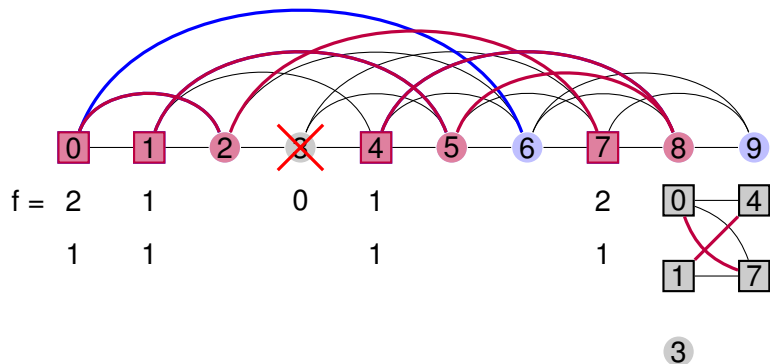
Finding spanning path system

$\mathcal{P} = \{0-6, 7, 9\}$

$\mathcal{Q} = \{0-2-7, 1-5-8-4\}$

$\mathcal{P} = ?$

$\mathcal{Q} = ?$



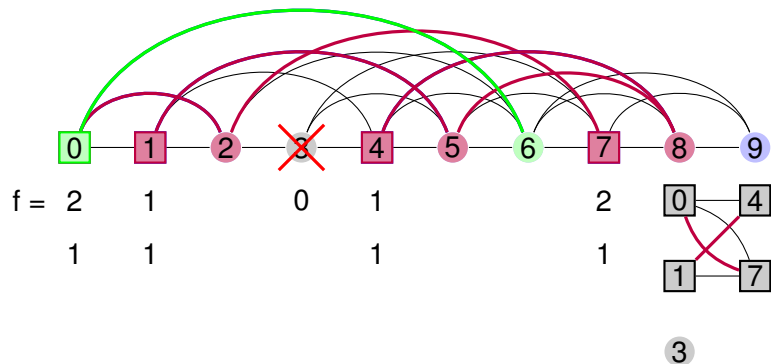
Finding spanning path system

$$\mathcal{P} = \{0-6, 7, 9\}$$

$$Q = \{0-2-7, 1-5-8-4\}$$

$$P = 0-6$$

$$Q = ?$$



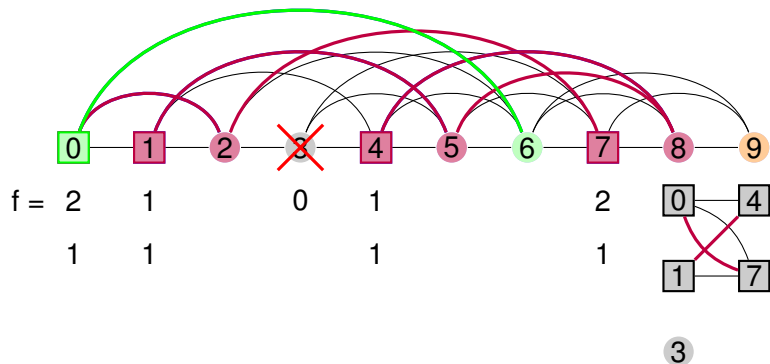
Finding spanning path system

$$\mathcal{P} = \{0-6, 7, 9\}$$

$$Q = \{0-2-7, 1-5-8-4\}$$

$$P = 0-6$$

$$Q = 9$$



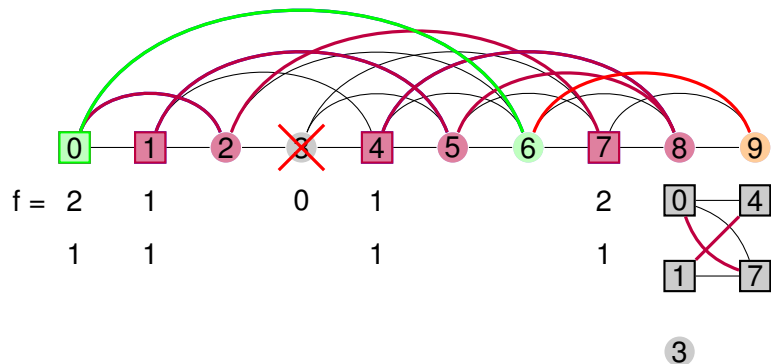
Finding spanning path system

$$\mathcal{P} = \{0-6, 7, 9\}$$

$$Q = \{0-2-7, 1-5-8-4\}$$

$$P = 0-6$$

$$Q = 9$$



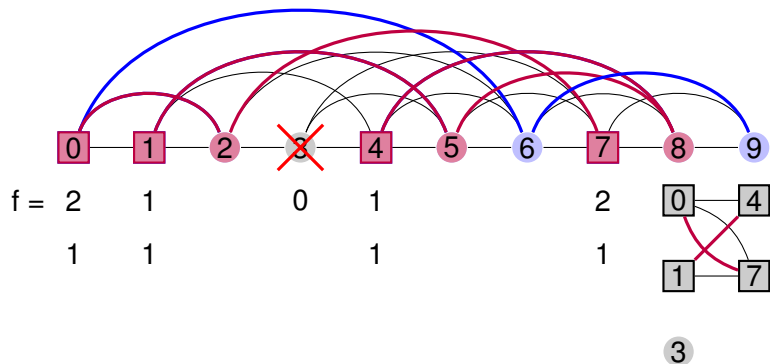
Finding spanning path system

$$\mathcal{P} = \{0-6-9, 7\}$$

$$\mathcal{Q} = \{0-2-7, 1-5-8-4\}$$

$$\mathcal{P} = ?$$

$$\mathcal{Q} = ?$$



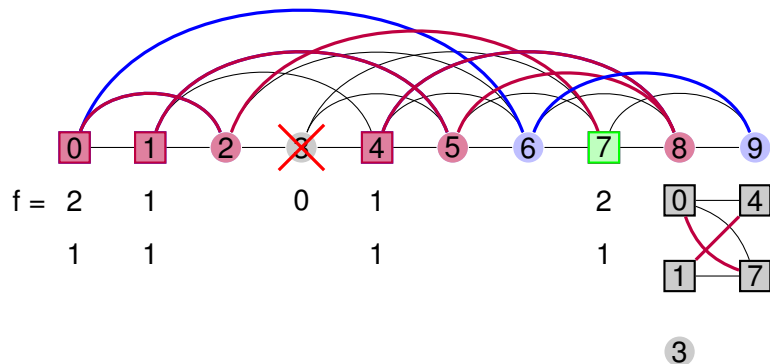
Finding spanning path system

$$\mathcal{P} = \{0-6-9, 7\}$$

$$Q = \{0-2-7, 1-5-8-4\}$$

$$P = 7$$

$$Q = ?$$



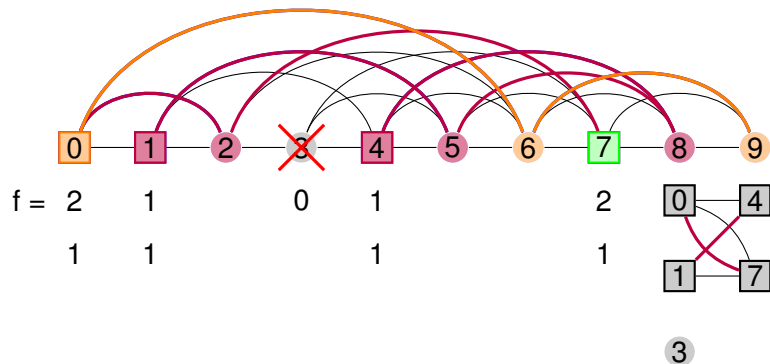
Finding spanning path system

$$\mathcal{P} = \{0-6-9, 7\}$$

$$Q = \{0-2-7, 1-5-8-4\}$$

$$P = 7$$

$$Q = 0-6-9$$



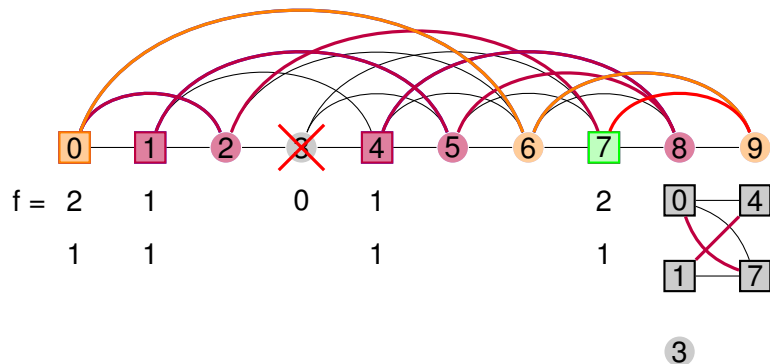
Finding spanning path system

$$\mathcal{P} = \{0-6-9, 7\}$$

$$Q = \{0-2-7, 1-5-8-4\}$$

$$P = 7$$

$$Q = 0-6-9$$



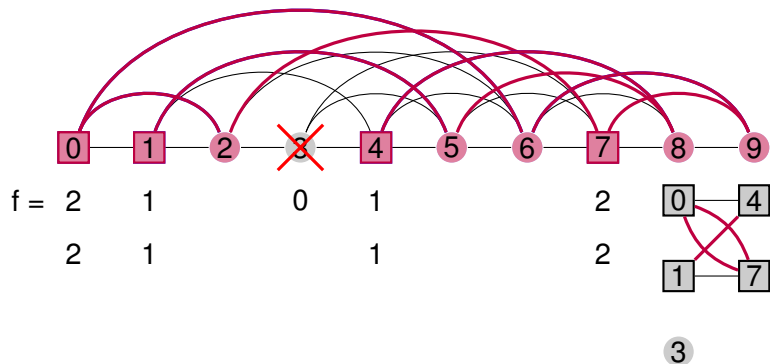
Finding spanning path system

$\mathcal{P} = \{\}$

$Q = \{0-2-7, 1-5-8-4, 0-6-9-7\}$

$P = ?$

$Q = ?$



A monotonicity lemma

Assume that the algorithm has been running successfully to produce the path family \mathcal{P}_t with $|E_{\mathcal{P}_t}| = t$ for some nonnegative integer t .

Let Σ_t be the set of **finished vertices** for \mathcal{P}_t .

Denote by Ω_t the family of **paths containing no fresh vertices** in the path family \mathcal{P}_t .

If $\pi_1 \in V_H \setminus f^{-1}(0)$, then

$$|\Sigma_t| + |\Omega_t| \leq |\Sigma_{t-1}| + |\Omega_{t-1}| \leq \cdots \leq |\Sigma_0| + |\Omega_0| = |f^{-1}(0)| + \sum_{v \in V_H} f(v).$$

Monotonicity of $|\Sigma_t| + |\Omega_t|$

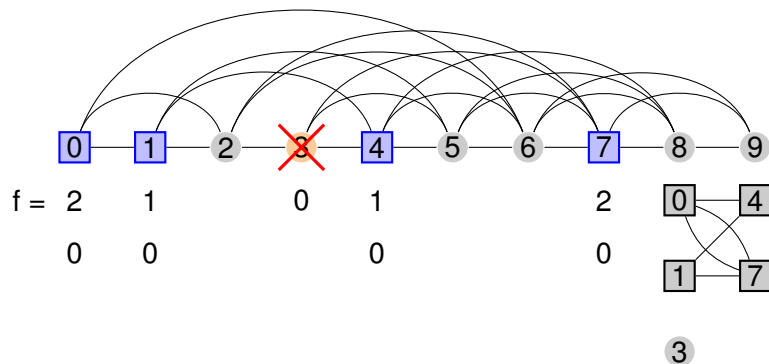
$t = 0$

$E = (0-2, 0-6, 1-5, 2-7, 4-8, 5-8, 6-9, 7-9)$

$\Sigma_t = \{3\}$

$\Omega_t = \{0, 0, 1, 4, 7, 7\}$

$|\Sigma_t| + |\Omega_t| = 7$



Monotonicity of $|\Sigma_t| + |\Omega_t|$

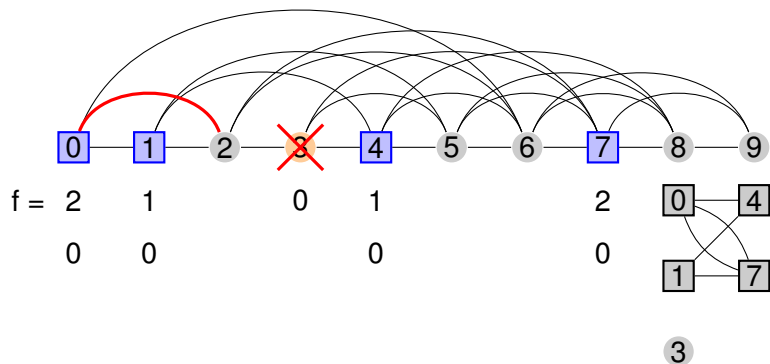
$t = 1$

$E = (0-2, 0-6, 1-5, 2-7, 4-8, 5-8, 6-9, 7-9)$

$\Sigma_t = \{3\}$

$\Omega_t = \{0, 0-2, 1, 4, 7, 7\}$

$|\Sigma_t| + |\Omega_t| = 7$



Monotonicity of $|\Sigma_t| + |\Omega_t|$

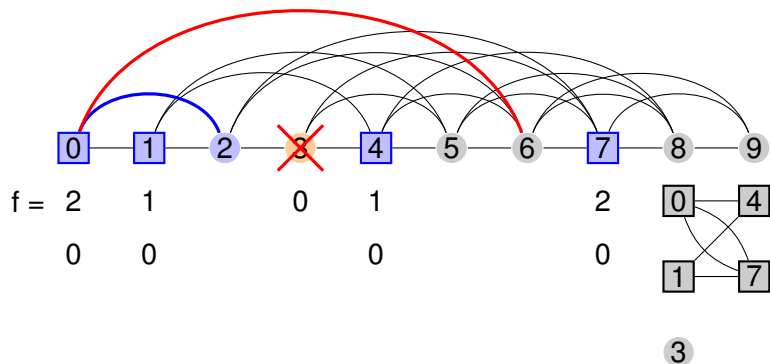
$t = 2$

$E = (0-2, 0-6, 1-5, 2-7, 4-8, 5-8, 6-9, 7-9)$

$\Sigma_t = \{3\}$

$\Omega_t = \{0-2, 0-6, 1, 4, 7, 7\}$

$|\Sigma_t| + |\Omega_t| = 7$



Monotonicity of $|\Sigma_t| + |\Omega_t|$

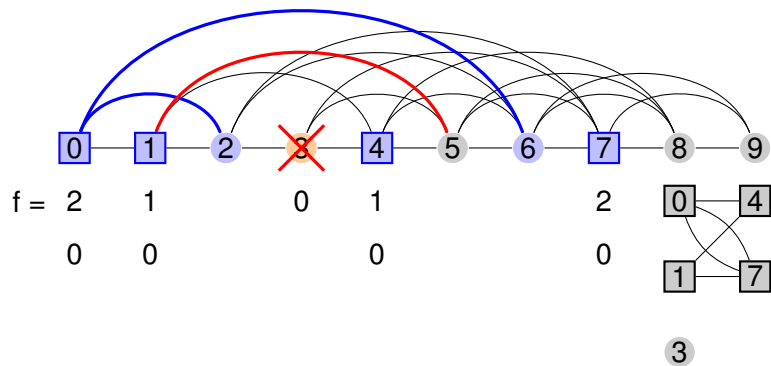
$t = 3$

$E = (0-2, 0-6, 1-5, 2-7, 4-8, 5-8, 6-9, 7-9)$

$\Sigma_t = \{3\}$

$\Omega_t = \{0-2, 0-6, 1-5, 4, 7, 7\}$

$|\Sigma_t| + |\Omega_t| = 7$



Monotonicity of $|\Sigma_t| + |\Omega_t|$

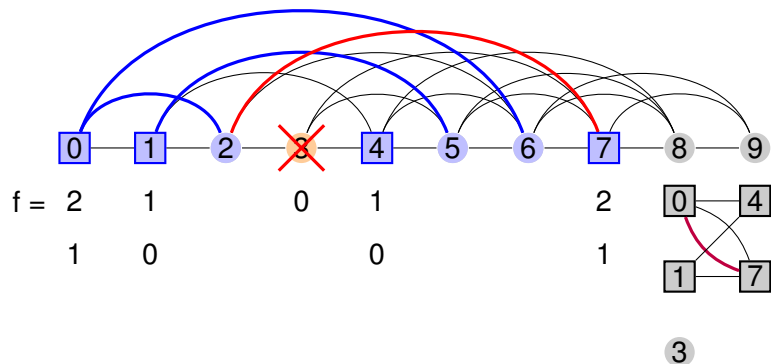
$t = 4$

$E = (0-2, 0-6, 1-5, 2-7, 4-8, 5-8, 6-9, 7-9)$

$\Sigma_t = \{3\}$

$\Omega_t = \{0-2-7, 0-6, 1-5, 4, 7\}$

$|\Sigma_t| + |\Omega_t| = 6$



Monotonicity of $|\Sigma_t| + |\Omega_t|$

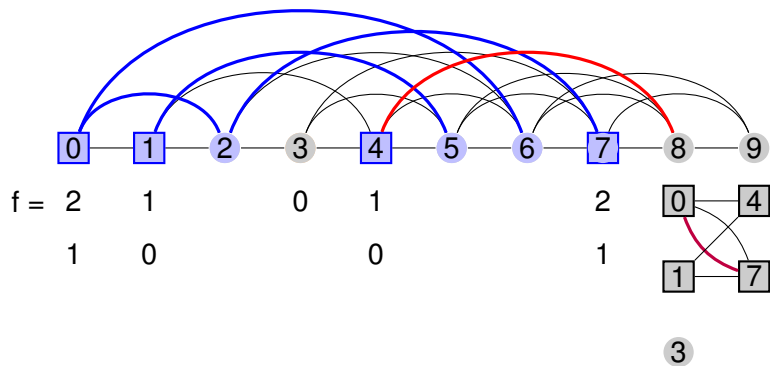
$t = 5$

$E = (0-2, 0-6, 1-5, 2-7, 4-8, 5-8, 6-9, 7-9)$

$\Sigma_t = \{\}$

$\Omega_t = \{0-2-7, 0-6, 1-5, 4-8, 7\}$

$|\Sigma_t| + |\Omega_t| = 5$



Monotonicity of $|\Sigma_t| + |\Omega_t|$

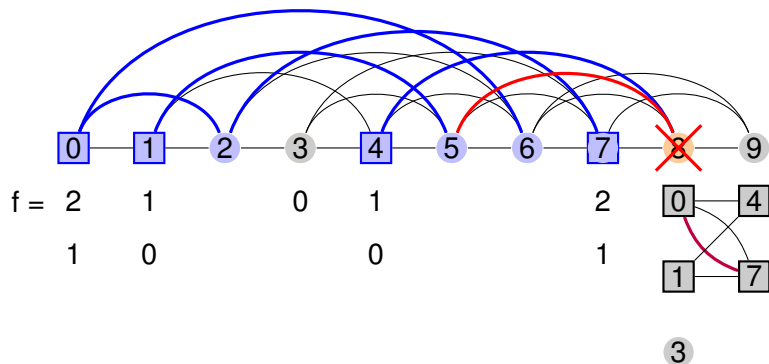
$t = 6$

$E = (0-2, 0-6, 1-5, 2-7, 4-8, 5-8, 6-9, 7-9)$

$\Sigma_t = \{8\}$

$\Omega_t = \{0-2-7, 0-6, 1-5-8-4, 7\}$

$|\Sigma_t| + |\Omega_t| = 5$



Monotonicity of $|\Sigma_t| + |\Omega_t|$

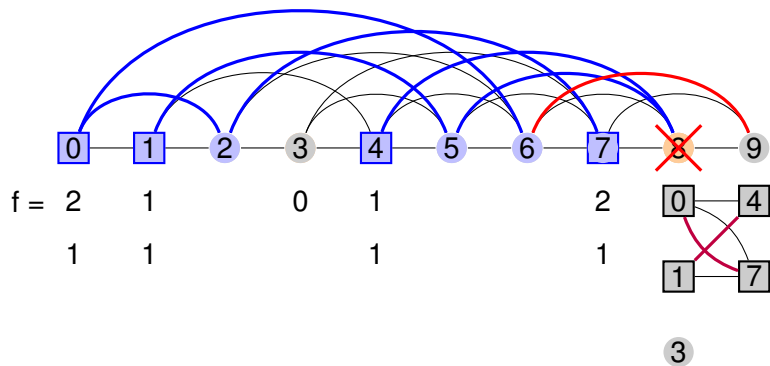
$t = 7$

$E = (0-2, 0-6, 1-5, 2-7, 4-8, 5-8, 6-9, 7-9)$

$\Sigma_t = \{8\}$

$\Omega_t = \{0-2-7, 0-6-9, 1-5-8-4, 7\}$

$|\Sigma_t| + |\Omega_t| = 5$



Monotonicity of $|\Sigma_t| + |\Omega_t|$

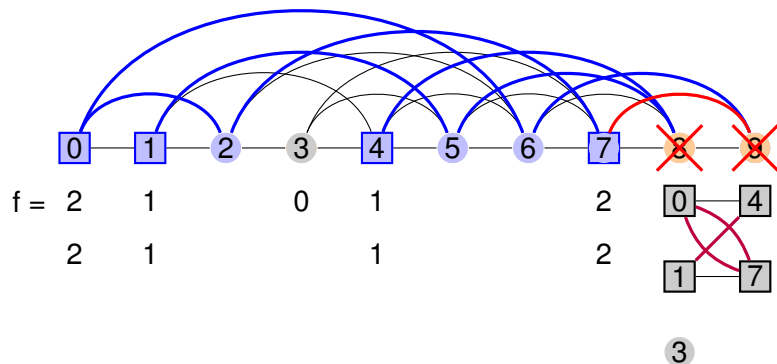
$t = 8$

$E = (0-2, 0-6, 1-5, 2-7, 4-8, 5-8, 6-9, 7-9)$

$\Sigma_t = \{8, 9\}$

$\Omega_t = \{0-2-7, 0-6-9-7, 1-5-8-4\}$

$|\Sigma_t| + |\Omega_t| = 5$



The end

Thank you

Tolerating edge failures

We can increase the Hamiltonian thickness bound by one to deal with every edge failure.

